MAKING MODERN LIVING POSSIBLE

Quick Guide

VLT® Micro Drive

VLT®
THE REAL DRIVE

Contents

1 Quick Guide

1.1 Safety

1.1.1 Warnings

⚠WARNING

HIGH VOLTAGE!

Adjustable frequency drives contain high voltage when connected to AC line power. Installation, start-up, and maintenance should be performed by qualified personnel only. Failure to perform installation, start-up, and maintenance by qualified personnel could result in death or serious injury.

High Voltage

Adjustable frequency drives are connected to hazardous AC line voltage. Extreme care should be taken to protect against shock. Only trained personnel familiar with electronic equipment should install, start, or maintain this equipment.

Touching the electrical parts may be fatal - even after the equipment has been disconnected from line power. Also make sure that other voltage inputs have been disconnected (linkage of DC intermediate circuit). Be aware that there may be high voltage on the DC link even when the LEDs are turned off. Before touching any potentially live parts of the adjustable frequency drive, wait at least 4 minutes for all M1, M2 and M3 sizes. Wait at least 15 minutes for all M4 and M5 sizes.

⚠WARNING

UNINTENDED START!

When the adjustable frequency drive is connected to AC line power, the motor may start at any time. The adjustable frequency drive, motor, and any driven equipment must be in operational readiness. Failure to be in operational readiness when the adjustable frequency drive is connected to AC line power could result in death, serious injury, equipment, or property damage.

Unintended Start

When the adjustable frequency drive is connected to the AC line power, the motor may be started by means of an external switch, a serial bus command, an input reference signal, or a cleared fault condition. Use appropriate cautions to guard against an unintended start.

Leakage Current (>3.5mA)

Follow national and local codes regarding protective grounding of equipment with a leakage current > 3.5mA. technology implies high frequency switching at high power. This will generate a leakage current in the ground connection. A fault current in the at the output power terminals might contain a DC component which can charge the filter capacitors and cause a transient ground current. The ground leakage current depends on various system configurations including RFI filtering, shielded motor cables, and power.

EN/IEC61800-5-1 (Power Drive System Product Standard) requires special care if the leakage current exceeds 3.5mA. Grounding must be reinforced in one of the following ways:

- Ground wire of at least 10mm^2.
- Two separate ground wires both complying with the dimensioning rules.

See EN 60364-5-54 § 543.7 for further information.

Using RCDs

Where residual current devices (RCDs), also known as ground leakage circuit breakers (ELCBs), are used, comply with the following:

Use RCDs of type B only which are capable of detecting AC and DC currents.

Use RCDs with an inrush delay to prevent faults due to transient ground currents.

Dimension RCDs according to the system configuration and environmental considerations.

Motor Thermal Protection

Motor overload protection is possible by setting Parameter 1-90 Motor thermal protection to the value ETR trip. For the North American market: Implemented ETR function provide class 20 motor overload protection, in accordance with NEC.

Installation at High Altitudes

For altitudes above 6,600 feet [2 km], please contact Danfoss regarding PELV.

1.1.2 Safety Instructions

- Make sure the adjustable frequency drive is properly grounded.
- Do not remove AC line input connections, motor connections or other power connections while the adjustable frequency drive is connected to line power.

- Protect users against supply voltage.
- Protect the motor against overloading according to national and local regulations.
- The ground leakage current exceeds 3.5 mA.
- The [Off/Reset] key is not a safety switch. It does not disconnect the adjustable frequency drive from line power.

1.2 Introduction

1.2.1 Available Literature

NOTE!

This Quick Guide contains the basic information necessary for installing and running the adjustable frequency drive.

If more information is needed, the literature below can be downloaded from:
http: //www.danfoss.com/BusinessAreas/DrivesSolutions/Documentations

Title	Literature no.
VLT Micro Drive FC 51 Design Guide	MG02K
VLT Micro Drive FC 51 Quick Guide	MG02B
VLT Micro Drive FC 51 Programming Guide	MG02C
FC 51 LCP Mounting Instruction	MI02A
FC 51 De-coupling Plate Mounting Instruction	MI02B
FC 51 Remote Mounting Kit Mounting Instruction	MI02C
FC 51 DIN Rail Kit Mounting Instruction	MI02D
FC 51 IP21 Kit Mounting Instruction	MI02E
FC 51 Nema1 Kit Mounting Instruction	MI02F
Line Filter MCC 107 Installation Instruction	MI02U

Table 1.1

1.2.2 Approvals

Table 1.2

1.2.3 IT Line Power

NOTE!

IT Line Power
Installation on an isolated line power source, i.e., IT line power.
Max. supply voltage allowed when connected to line power: 440 V.

As an option, Danfoss offers recommended line filters for improved harmonics performance.

1.2.4 Avoid Unintended Start

While the adjustable frequency drive is connected to line power, the motor can be started/stopped using digital commands, bus commands, references or via the LCP.

- Disconnect the adjustable frequency drive from line power whenever personal safety considerations make it necessary to avoid unintended start of any motors.
- To avoid unintended start, always press [Off/ Reset] before changing parameters.

1.2.5 Disposal Instruction

Equipment containing electrical components may not be disposed of together with domestic waste.
It must be separately collected with electrical and electronic waste according to local and currently valid legislation.

Table 1.3

1.3 Installation

1. Disconnect FC 51 from line power (and external DC supply, if present.)
2. Wait for 4 min (M1, M2 and M3) and 15 min (M4 and M5) for discharge of the DC link. See .
3. Disconnect DC bus terminals and brake terminals (if present).
4. Remove motor cable.

1.3.1 Side-by-Side Installation

The adjustable frequency drive can be mounted side-by-side for IP20 rating units and requires 4 in [100 mm] clearance above and below for cooling. Refer to the specifications near the end of this document for details on environmental ratings for the adjustable frequency drive.

1.3.2 Mechanical Dimensions

A template for drilling can be found on the flap of the packaging.

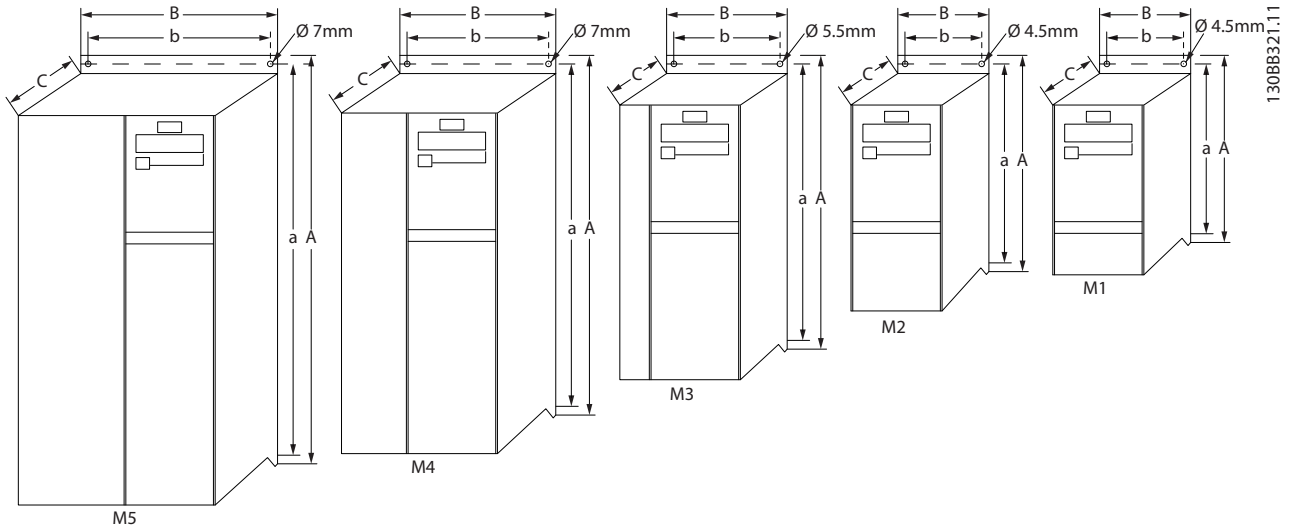


Figure 1.1 Mechanical Dimensions

	Power [kW]			Height (in [mm])			Width (in [mm])		Depth [1] (in [mm])	Max. Weight
Frame	1X200–240 V	3X200–240 V	3X380–480 V	A	A (incl. decoupling plate)	a	B	b	C	lbs [kg]
M1	0.25–1 [0.18–0.75]	0.34–1 [0.25–0.75]	0.5–1 [0.37–0.75]	5.91 [150]	8.1 [205]	5.53 [140.4]	2.76 [70]	2.17 [55]	5.83 [148]	2.43 [1.1]
M2	2 [1.5]	2 [1.5]	2–3 [1.5–2.2]	6.93 [176]	9.06 [230]	6.6 [166.4]	2.95 [75]	2.32 [59]	6.61 [168]	3.53 [1.6]
M3	3 [2.2]	3–5 [2.2–3.7]	4–10 [3.0–7.5]	9.41 [239]	11.58 [294]	8.9 [226]	3.54 [90]	2.72 [69]	7.64 [194]	6.6 [3.0]
M4			15–20 [11.0–15.0]	11.5 [292]	13.7 [347.5]	10.72 [272.4]	4.92 [125]	3.82 [97]	9.5 [241]	13.23 [6.0]
M5			25–30 [18.5–22.0]	13.2 [335]	15.26 [387.5]	12.4 [315]	6.5 [165]	5.51 [140]	9.76 [248]	20.94 [9.5]

[1] For LCP with potentiometer, add 0.3 in [7.6 mm].

Table 1.4 Mechanical Dimensions

1.3.3 Electrical Installation in General

NOTE!

All cabling must comply with national and local regulations on cable cross-sections and ambient temperature. Copper conductors required, (140°–167°F [60°–75°C]) recommended.

	Power (HP [kW])			Torque (Nm)					
Frame Size	1 x 200–240V	3 x 200–240V	3 x 380–480V	Line	Motor	DC connection/Brake	Control Terminals	Ground	Relay
M1	0.24–1 [0.18–0.75]	0.34–1 [0.25–0.75]	0.5–1 [0.37–0.75]	1.4	0.7	Spade[1)]	0.15	3	0.5
M2	2 [1.5]	2 [1.5]	2–3 [1.5–2.2]	1.4	0.7	Spade[1)]	0.15	3	0.5
M3	3 [2.2]	3–5 [2.2–3.7]	4–10 [3.0–7.5]	1.4	0.7	Spade[1)]	0.15	3	0.5
M4			15–20 [11.0–15.0]	1.3	1.3	1.3	0.15	3	0.5
M5			25–30 [18.5–22.0]	1.3	1.3	1.3	0.15	3	0.5

[1)] Spade connectors (0.25 in [6.3 mm] Faston plugs)

Table 1.5 Tightening of Terminals

1.3.4 Fuses

Branch circuit protection:
In order to protect the installation against electrical and fire hazards, all branch circuits in an installation, switch gear, machines, etc. must be short-circuited and overcurrent protected according to national/international regulations.

Short circuit protection:
Danfoss recommends using the fuses mentioned in the following tables to protect service personnel or other equipment in case of an internal failure in the unit or short-circuit on the DC link. The adjustable frequency drive provides full short circuit protection in case of a short-circuit on the motor or brake output.

Provide overload protection to avoid overheating of the cables in the installation. Overcurrent protection must always be carried out according to national regulations. Fuses must be designed for protection in a circuit capable of supplying a maximum of 100,000 A_{rms} (symmetrical), 480V maximum.

Non UL compliance:
If UL/cUL is not to be complied with, Danfoss recommends using the fuses mentioned in the table below, which will ensure compliance with EN50178/IEC61800-5-1:
In case of malfunction, not following the fuse recommendation may result in damage to the adjustable frequency drive.

Overcurrent protection:

FC 51	Max. Fuses UL						Max. fuses non-UL
	Bussmann	Bussmann	Bussmann	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut	
1 X 200–240V							
kW	Type RK1	Type J	Type T	Type RK1	Type CC	Type RK1	Type gG
0K18 - 0K37	KTN-R15	JKS-15	JJN-15	KLN-R15	ATM-R15	A2K-15R	16A
0K75	KTN-R25	JKS-25	JJN-25	KLN-R25	ATM-R25	A2K-25R	25A
1K5	KTN-R35	JKS-35	JJN-35	KLN-R35	-	A2K-35R	35A
2K2	KTN-R50	JKS-50	JJN-50	KLN-R50	-	A2K-50R	50A
3 x 200–240V							
0K25	KTN-R10	JKS-10	JJN-10	KLN-R10	ATM-R10	A2K-10R	10A
0K37	KTN-R15	JKS-15	JJN-15	KLN-R15	ATM-R15	A2K-15R	16A
0K75	KTN-R20	JKS-20	JJN-20	KLN-R20	ATM-R20	A2K-20R	20A
1K5	KTN-R25	JKS-25	JJN-25	KLN-R25	ATM-R25	A2K-25R	25A
2K2	KTN-R40	JKS-40	JJN-40	KLN-R40	ATM-R40	A2K-40R	40A
3K7	KTN-R40	JKS-40	JJN-40	KLN-R40	-	A2K-40R	40A
3 x 380–480V							
0K37 - 0K75	KTS-R10	JKS-10	JJS-10	KLS-R10	ATM-R10	A6K-10R	10A
1K5	KTS-R15	JKS-15	JJS-15	KLS-R15	ATM-R15	A2K-15R	16A
2K2	KTS-R20	JKS-20	JJS-20	KLS-R20	ATM-R20	A6K-20R	20A
3K0	KTS-R40	JKS-40	JJS-40	KLS-R40	ATM-R40	A6K405R	40A
4K0	KTS-R40	JKS-40	JJS-40	KLS-R40	ATM-R40	A6K-40R	40A
5K5	KTS-R40	JKS-40	JJS-40	KLS-R40	-	A6K-40R	40A
7K5	KTS-R40	JKS-40	JJS-40	KLS-R40	-	A6K-40R	40A
11K0	KTS-R60	JKS-60	JJS-60	KLS-R60	-	A6K-60R	63A
15K0	KTS-R60	JKS-60	JJS-60	KLS-R60	-	A6K-60R	63A
18K5	KTS-R60	JKS-60	JJS-60	KLS-R60	-	A6K-60R	80A
22K0	KTS-R60	JKS-60	JJS-60	KLS-R60	-	A6K-60R	80A

Table 1.6 Fuses

1.3.5 Connecting to Line Power and Motor

The adjustable frequency drive is designed to operate all standard three-phased asynchronous motors.
The adjustable frequency drive is designed to accept line power/motor cables with a maximum cross-section of 0.006 in^2 [4 mm^2]/10 AWG (M1, M2 and M3) and maximum cross-section 0.0248 in^2 [16 mm^2]/6 AWG (M4 and M5).

- Use a shielded/armored motor cable to comply with EMC emission specifications, and connect this cable to both the decoupling plate and the motor metal.
- Keep motor cable as short as possible to reduce the noise level and leakage currents.
- For further details on mounting of the decoupling plate, see *Instruction MI02B*.
- Also see EMC-Compatible Installation in *Design Guide MG02K*.

1. Mount the ground wires to the ground terminal.
2. Connect the motor to terminals U, V and W.
3. Mount line power supply to terminals L1/L, L2 and
   L3/N (3-phase) or L1/L and L3/N (single-phase) and tighten.

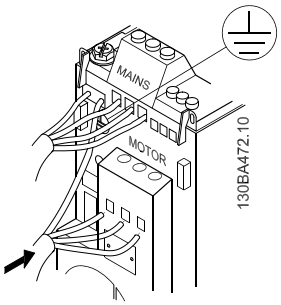


Figure 1.2 Mounting of Ground Cable, Line Power and Motor Wires

1.3.6 Control Terminals

All control cable terminals are located underneath the terminal cover in front of the adjustable frequency drive. Remove the terminal cover using a screwdriver.

NOTE!

See back of terminal cover for outlines of control terminals and switches.

NOTE!

Do not operate switches with power on the adjustable frequency drive.
***6-19 Terminal 53 Mode* must be set according to Switch 4 position.**

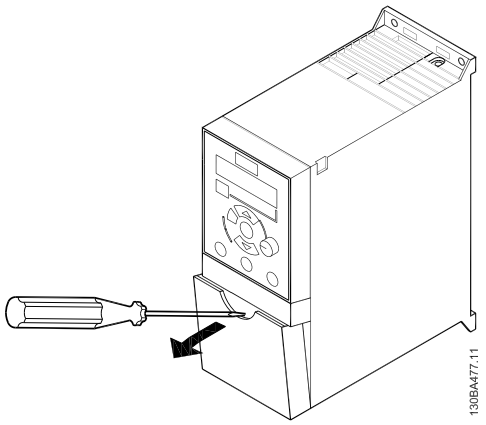


Figure 1.3 Removing Terminal Cover

Switch 1:	*OFF=PNP terminals 29
	ON=NPN terminals 29
Switch 2:	*OFF=PNP terminal 18, 19, 27 and 33
	ON=NPN terminal 18, 19, 27 and 33
Switch 3:	No function
Switch 4:	*OFF=Terminal 53 0–10 V
	ON=Terminal 53 0/4–20 mA
*=default setting	

Table 1.7 Settings for S200 Switches 1-4

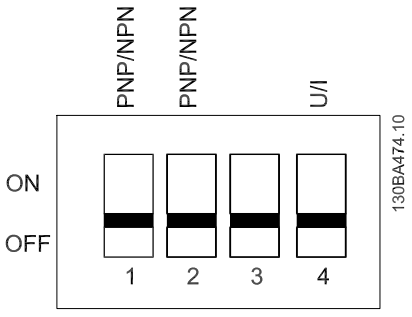


Figure 1.4 S200 Switches 1-4

Figure 1.5 shows all control terminals of the adjustable frequency drive. Applying Start (term. 18) and an analog

reference (term. 53 or 60) makes the adjustable frequency drive run.

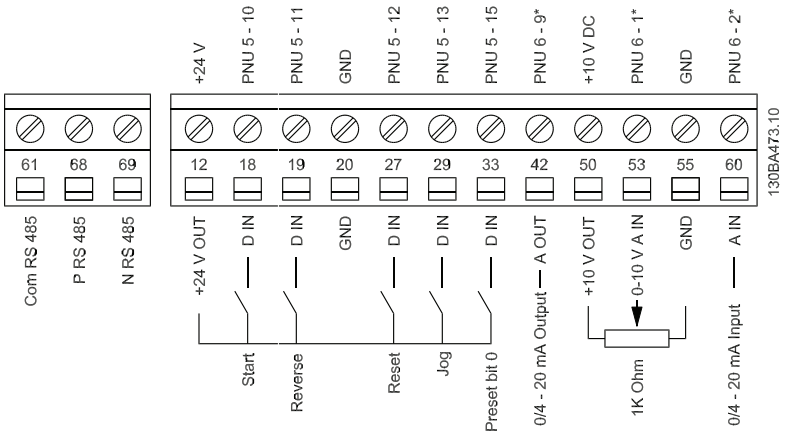


Figure 1.5 Overview of Control Terminals in PNP configuration and Factory Settings

1.3.7 Power Circuit - Overview

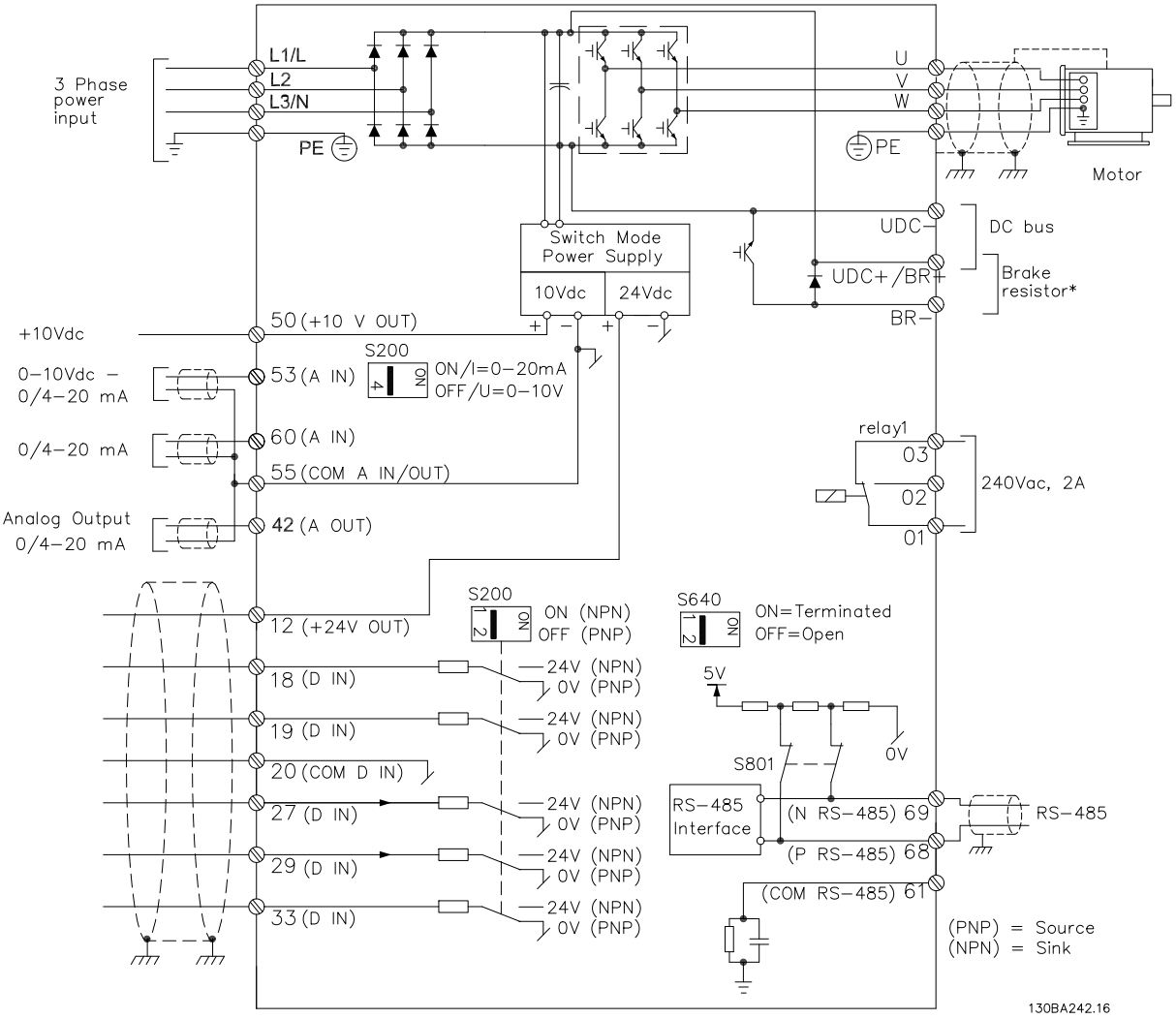


Figure 1.6 Diagram Showing all Electrical Terminals

* Brake (BR+ and BR-) are not applicable for frame M1.

Brake resistors are available from Danfoss.
Improved power factor and EMC performance can be achieved by installing optional Danfoss line filters.
Danfoss power filters can also be used for load sharing.

1.3.8 Load Sharing/Brake

Use 0.25 in [6.3 mm] insulated Faston plugs designed for high voltage for DC (load sharing and brake).
Contact Danfoss or see *Instruction MI50N* for load sharing and *Instruction MI90F* for brake.

Load sharing: Connect terminals -UDC and +UDC/+BR.
Brake: Connect terminals -BR and +UDC/+BR (Not applicable for frame M1).

NOTE!

Voltage levels of up to 850 V DC may occur between terminals
+UDC/+BR and -UDC. Not short circuit-protected.

1.4 Programming

1.4.1 Programming with LCP

For detailed information on programming, see *Programming Guide*, MG02C.

NOTE!

The adjustable frequency drive can also be programmed from a PC via RS-485 COM port by installing the MCT 10 Set-up Software.
This software can either be ordered using code number 130B1000 or downloaded from the Danfoss website: ***www.danfoss.com/BusinessAreas/DrivesSolutions/software-download***

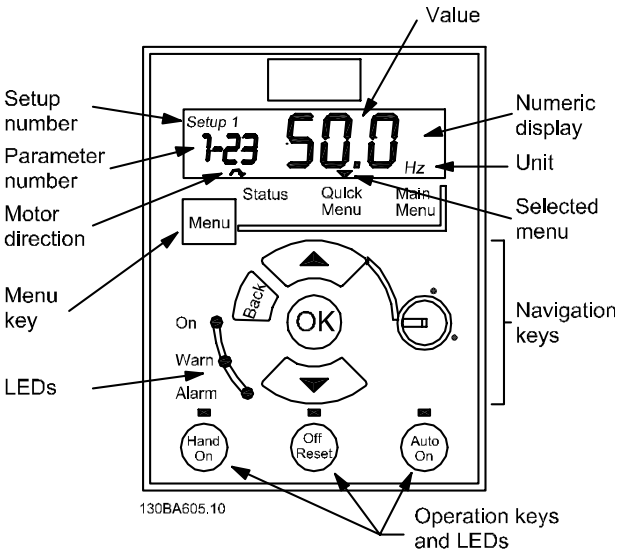


Figure 1.7 Description of LCP Buttons and Display

Use the [Menu] key to select one of the following menus:

Status
For readouts only.

Quick Menu
For access to Quick Menus 1 and 2, respectively.

Main Menu
For access to all parameters.

Navigation Keys
[Back]: For moving to the previous step or layer in the navigation structure.
[▲] [▼]: For navigating between parameter groups, parameters and within parameters.

[OK]: For selecting a parameter and for accepting changes to parameter settings.

Pressing [OK] for more than 1 s enters 'Adjust' mode. In 'Adjust' mode, it is possible to make fast adjustment by pressing [▲] [▼] combined with [OK].

Press [▲] [▼] to change value. Press [OK] to shift between digits quickly.

To exit 'Adjust' mode, press [OK] more than 1 s again with changes saving or press [Back] without changes saving.

Operation Keys
A yellow light above the operation keys indicates the active key.
[Hand on]: Starts the motor and enables control of the adjustable frequency drive via the LCP.
[Off/Reset]: The motor stops except when in alarm mode, in which case, the motor will be reset.
[Auto on]: The adjustable frequency drive is controlled either via control terminals or serial communication.
[Potentiometer] (LCP12): The potentiometer works in two ways depending on the mode in which the adjustable frequency drive is running.
In *Auto Mode*, the potentiometer acts as an extra programmable analog input.
In *Hand on Mode,* the potentiometer controls local reference.

1.5 Parameter Overview

Parameter Overview			
0-** Operation/Display	*[0] Constant torque	**1-63 Slip Compensation Time Constant**	**3-03 Maximum Reference**
0-0* Basic Settings	[2] Automatic Energy Optim.	0.05–5.00 s * 0.10 s	-4,999–4,999 * 50.00
0-03 Regional Settings	**1-05 Local Mode Configuration**	***1-7* Start Adjustments***	***3-1* References***
*[0] International	[0] Speed Open-loop	**1-71 Start Delay**	**3-10 Preset Reference**
[1] US	*[2] As config in par. 1-00 ***1-2* Motor Data***	0.0–10.0 s * 0.0 s	-100.0–100.0% * 0.00%
0-04 Oper. State at Power-up (Hand)	**1-20 Motor Power [kW] [HP]**	**1-72 Start Function**	**3-11 Jog Speed [Hz]**
[0] Resume	[1] 0.09 kW/0.12 HP	[0] DC Hold/delay time	0.0–400.0 Hz * 5.0 Hz
*[1] Forced stop, ref=old	[2] 0.12 kW/0.16 HP	[1] DC brake/delay time	**3-12 Catch up/Slow-down Value**
[2] Forced stop, ref=0	[3] 0.18 kW/0.25 HP	*[2] Coast/delay time	0.00–100.0% * 0.00%
0-1* Setup Handling	[4] 0.25 kW/0.33 HP	**1-73 Flying Start**	**3-14 Preset Relative Reference**
0–10 Active Setup	[5] 0.37 kW/0.50 HP	*[0] Disabled	-100.0–100.0% * 0.00% **3-15 Reference Resource 1**
*[1] Setup 1	[6] 0.55 kW/0.75 HP	[1] Enabled	[0] No function
[2] Setup 2	[7] 0.75 kW/1.00 HP	***1-8* Stop Adjustments***	*[1] Analog Input 53
[9] Multi Setup	[8] 1.10 kW/1.50 HP	**1-80 Function at Stop**	[2] Analog input 60
0-11 Edit Setup	[9] 1.50 kW/2.00 HP	*[0] Coast	[8] Pulse input 33
*[1] Setup 1	[10] 2.20 kW/3.00 HP	[1] DC hold	[11] Local bus ref
[2] Setup 2	[11] 3.00 kW/4.00 HP	**1-82 Min Speed for Funct. at Stop [Hz]**	[21] Potentiometer
[9] Active Setup	[12] 3.70 kW/5.00 HP	0.0–20.0 Hz * 0.0 Hz	**3-16 Reference Resource 2**
0-12 Link Setups	[13] 4.00 kW/5.40 HP	***1-9*Motor Temperature***	[0] No function
[0] Not Linked	[14] 5.50 kW/7.50 HP	**1-90 Motor Thermal Protection**	[1] Analog Input 53
*[20] Linked	[15] 7.50 kW/10.00 HP	*[0] No protection	*[2] Analog input 60
0-31 Custom Readout Min Scale	[16] 11.00 kW/15.00 HP	[1] Thermistor warning	[8] Pulse input 33
0.00–9,999.00 * 0.00	[17] 15.00 kW/20.00 HP	[2] Thermistor trip	*[11] Local bus ref
0-32 Custom Readout Max Scale	[18] 18.50 kW/25.00 HP	[3] ETR warning	[21] Potentiometer
0.00–9,999.00 * 100.0	[19] 22.00 kW/29.50 HP	[4] Etr trip	**3-17 Reference Resource 3**
0-4* Keypad	[20] 30.00 kW/40.00 HP	**1-93 Thermistor Resource**	[0] No function
0-40 [Hand on] Key on	**1-22 Motor Voltage**	*[0] None	[1] Analog Input 53
[0] Disabled	50–999 V *230–400 V	[1] Analog input 53	[2] Analog input 60
*[1] Enabled	**1-23 Motor Frequency**	[6] Digital input 29	[8] Pulse input 33
0-41 [Off / Reset] Key on	20–400 Hz *50 Hz	***2-** Brakes***	*[11] Local bus ref
[0] Disable All	**1-24 Motor Current**	***2-0*DC Brake***	[21] Potentiometer
*[1] Enable All	0.01–100.00 A *Motortype dep.	**2-00 DC Hold Current**	**3-18 Relative Scaling Ref. Resource**
[2] Enable Reset Only	**1-25 Motor Nominal Speed**	0–150% * 50%	*[0] No function
0-42 [Auto on] Key on	100–9,999 rpm *Motortype dep.	**2-01 DC Brake Current**	[1] Analog Input 53
[0] Disabled	**1-29 Automatic Motor Tuning (AMT)**	0–150% * 50%	[2] Analog input 60
*[1] Enabled	*[0] Off	**2-02 DC Braking Time**	[8] Pulse input 33
0-5* Copy/Save	[2] Enable AMT	0.0–60.0 s * 10.0s	[11] Local bus ref
0–50 Copy	***1-3* Adv. Motor Data***	**2-04 DC Brake Cut In Speed**	[21] Potentiometer
*[0] No copy	**1-30 Stator Resistance (Rs)**	0.0–400.0 Hz * 0.0 Hz	***3-4* Ramp 1***
[1] All to	[Ohm] * Dep. on motor data	***2-1* Brake Energy Funct.***	**3-40 Ramp 1 Type**
[2] All from	**1-33 Stator Leakage Reactance (X1)**	**2-10 Brake Function**	*[0] Linear
[3] Size indep. from	[Ohm] * Dep. on motor data	*[0] Off	[2] Sine2 ramp
0-51 Setup Copy	**1-35 Main Reactance (Xh)**	[1] Resistor brake	**3-41 Ramp 1 Ramp-up Time**
*[0] No copy	[Ohm] * Dep. on motor data	[2] AC brake	0.05–3,600 s * 3.00 s (10.00 s[1)])
[1] Copy from Setup 1	***1-5* Load Indep. Setting***	**2-11 Brake Resistor (ohm)**	**3-42 Ramp 1 Ramp-down Time**
[2] Copy from Setup 2	**1-50 Motor Magnetization at 0 Speed**	5–5,000 * 5	0.05–3,600 s * 3.00s (10.00s [1)])
[9] Copy from Factory Setup	0–300% *100%	**2-16 AC Brake, Max current**	***3-5* Ramp 2***
0-6* Password	**1-52 Min Speed Norm. Magnet. [Hz]**	0–150% * 100%	**3-50 Ramp 2 Type**
0-60 (Main) Menu Password	0.0–10.0 Hz *0.0 Hz	**2-17 Over-voltage Control**	*[0] Linear
0–999 *0	**1-55 U/f Characteristic - U**	*[0] Disabled	[2] Sine2 ramp
0-61 Access to Main/Quick Menu w/o Password	0–999.9 V	[1] Enabled (not at stop)	**3-51 Ramp 2 Ramp-up Time**
*[0] Full access	**1-56 U/f Characteristic - F**	[2] Enabled	0.05–3,600 s * 3.00 s (10.00 s [1)])
[1] LCP: Read Only	0–400 Hz	***2-2* Mechanical Brake***	**3-52 Ramp 2 Ramp-down Time**
[2] LCP: No Access	***1-6* Load Depen. Setting***	**2-20 Release Brake Current**	0.05–3,600 s * 3.00 s (10.00 s[1)])
1-** Load/Motor	**1-60 Low Speed Load Compensation**	0.00–100.0 A * 0.00 A	***3-8* Other Ramps***
1-0* General Settings	0–199% *100%	**2-22 Activate Brake Speed [Hz]**	**3-80 Jog Ramp Time**
1-00 Configuration Mode	**1-61 High Speed Load Compensation**	0.0–400.0 Hz * 0.0 Hz	0.05–3,600 s * 3.00 s (10.00s[1)])
*[0] Speed open-loop	0–199% *100%	***3-** Reference / Ramps***	**3-81 Quick Stop Ramp Time**
[3] Process	**1-62 Slip Compensation**	***3-0* Reference Limits***	0.05–3,600 s * 3.00 s (10.00s[1)])
1-01 Motor Control Principle	-400–399% *100%	**3-00 Reference Range**	***4-** Limits/Warnings***
[0] U/f		*[0] Min. - Max.	***4-1* Motor Limits***
*[1] VVC+		[1] -Max - +Max	**4-10 Motor Speed Direction**
1-03 Torque Characteristics		**3-02 Minimum Reference**	*[0] Clockwise If Par. 1-00 is set to close-loop control
		-4,999–4,999 * 0.000	

[1)] M4 and M5 only

Table 1.8

[1]CounterClockwise
*[2] Both if Par. 1-00 is set to open-loop control
4-12 Motor Speed Low Limit [Hz]
0.0–400.0 Hz * 0.0 Hz
4-14 Motor Speed High Limit [Hz]
0.1–400.0 Hz * 65.0 Hz
4-16 Torque Limit Motor Mode
0–400% * 150%
4-17 Torque Limit Generator Mode
0–400% * 100%
4-4* Adj. Warnings 2
4-40 Warning Frequency Low
0.00–Value of 4-41 Hz * 0.0 Hz
4-41 Warning Frequency High
Value of 4-40–400.0 Hz * 400.00 Hz
4-5* Adj. Warnings
4-50 Warning Current Low
0.00–100.00 A * 0.00 A
4-51 Warning Current High
0.0–100.00 A * 100.00 A
4-54 Warning Reference Low
-4,999.000–Value of 4-55
* -4,999.000
4-55 Warning Reference High
Value of 4-54 -4,999.000
* 4,999.000
4-56 Warning Feedback Low
-4,999.000–Value of 4-57
* -4,999.000
4-57 Warning Feedback High
Value of 4-56-4,999.000 * 4,999.000
4-58 Missing Motor Phase Function
[0] Off
*[1] On
4-6* Speed Bypass
4-61 Bypass Speed From [Hz]
0.0–400.0 Hz * 0.0 Hz
4-63 Bypass Speed To [Hz]
0.0–400.0 Hz * 0.0 Hz
5-1* Digital Inputs
5-10 Terminal 18 Digital Input
[0] No function
[1] Reset
[2] Coast inverse
[3] Coast and reset inv.
[4] Quick stop inverse
[5] DC brake inv.
[6] Stop inv
*[8] Start
[9] Latched start
[10] Reversing
[11] Start reversing
[12] Enable start forward
[13] Enable start reverse
[14] Jog
[16-18] Preset ref bit 0-2
[19] Freeze reference
[20] Freeze output
[21] Speed up
[22] Slow
[23] Set-up select bit 0
[28] Catch up
[29] Slow-down
[34] Ramp bit 0
[60] Counter A (up)
[61] Counter A (down)
[62] Reset counter A
[63] Counter B (up)
[64] Counter B (down)
[65] ResetCounter B
5-11 Terminal 19 Digital Input
See par. 5-10. * [10] Reversing
5-12 Terminal 27 Digital Input
See par. 5-10. * [1] Reset
5-13 Terminal 29 Digital Input
See par. 5-10. * [14] Jog
5-15 Terminal 33 Digital Input
See par. 5-10. * [16] Preset ref bit 0
[26] Precise Stop Inverse
[27] Start, Precise Stop
[32] Pulse Input
5-3* Digital Outputs
5-34 On Delay, Terminal 42 Digital Output
0.00–600.00 s * 0.01 s
5-35 Off Delay, Terminal 42 Digital Output
0.00–600.00 s * 0.01 s
5-4* Relays
5-40 Function Relay
*[0] No operation
[1] Control ready
[2] Drive ready
[3] Drive ready, Remote
[4] Enable / No warning
[5] Drive running
[6] Running / No warning
[7] Run in range / No warning
[8] Run on ref / No warning
[9] Alarm
[10] Alarm or warning
[12] Out of current range
[13] Below current, low
[14] Above current, high
[16] Below frequency, low
[17] Above frequency, high
[19] Below feedback, low
[20] Above feedback, high
[21] Thermal warning
[22] Ready, No thermal warning
[23] Remote ready, No thermal warning
[24] Ready, Voltage ok
[25] Reverse
[26] Bus ok
[28] Brake, NoWarn
[29] Brake ready/NoFault
[30] BrakeFault (IGBT)
[32] Mech.brake control
[36] Control word bit 11
[41] Below reference, low
[42] Above reference, high
[51] Local ref. active
[52] Remote ref. active
[53] No alarm
[54] Start cmd active
[55] Running reverse
[56] Drive in hand mode
[57] Drive in auto mode
[60-63] Comparator 0-3
[70-73] Logic rule 0-3
[81] SL digital output B
5-41 On Delay, Relay
0.00–600.00 s * 0.01 s
5-42 Off Delay, Relay
0.00–600.00 s * 0.01 s
5-5* Pulse Input
5-55 Terminal 33 Low Frequency
20–4,999 Hz * 20 Hz
5-56 Terminal 33 High Frequency
21–5,000 Hz * 5,000 Hz
5-57 Term. 33 Low Ref./Feedb. Value
-4,999–4,999 * 0.000
5-58 Term. 33 High Ref./Feedb. Value
-4,999–4,999 * 50.000
6-** Analog In/Out
6-0* Analog I/O Mode
6-00 Live Zero Timeout Time
1-99 s * 10 s
6-01 Live Zero Timeout Function
*[0] Off
[1] Freeze output
[2] Stop
[3] Jogging
[4] Max. speed
[5] Stop and trip
6-1* Analog Input 1
6-10 Terminal 53 Low Voltage
0.00–9.99 V * 0.07 V
6-11 Terminal 53 High Voltage
0.01–10.00 V * 10.00 V
6-12 Terminal 53 Low Current
0.00–19.99 mA * 0.14 mA
6-13 Terminal 53 High Current
0.01–20.00 mA * 20.00 mA
6-14 Term. 53 Low Ref./Feedb. Value
-4,999–4,999 * 0.000
6-15 Term. 53 High Ref./Feedb. Value
-4,999–4,999 * 50.000
6-16 Terminal 53 Filter Time Constant
0.01–10.00 s * 0.01 s
6-19 Terminal 53 mode
*[0] Voltage mode
[1] Current mode
6-2* Analog Input 2
6-22 Terminal 60 Low Current
0.00–19.99 mA * 0.14 mA
6-23 Terminal 60 High Current
0.01–20.00 mA * 20.00 mA
6-24 Term. 60 Low Ref./Feedb. Value
-4,999–4,999 * 0.000
6-25 Term. 60 High Ref./Feedb. Value
-4,999–4,999 * 50.00
6-26 Terminal 60 Filter Time Constant
0.01–10.00 s * 0.01 s
6-8* potentiometer
6-80 LCP Potmeter Enable
[0] Disabled
*[1] Enable
6-81 potm. Low Reference
-4,999–4,999 * 0.000
6-82 potm. High Reference
-4,999–4,999 * 50.00
6-9* Analog Output xx
6-90 Terminal 42 Mode
*[0] 0–20 mA
[1] 4–20 mA
[2] Digital Output
6-91 Terminal 42 Analog Output
*[0] No operation
[10] Output Frequency
[11] Reference
[12] Feedback
[13] Motor Current
[16] Power
[20] Bus Reference
6-92 Terminal 42 Digital Output
See par. 5-40
*[0] No Operation
[80] SL Digital Output A
6-93 Terminal 42 Output Min Scale
0.00–200.0% * 0.00%
*[0] No Operation
[80] Logic Controller Digital Output A
6-93 Terminal 42 Output Min Scale
0.00–200.0% * 0.00%
6-94 Terminal 42 Output Max Scale
0.00–200.0% * 100.0%
7-** Controllers
7-2* Process Ctrl. Feedb
7-20 Process CL Feedback 1 Resource
*[0] NoFunction
[1] Analog Input 53
[2] Analog input 60
[8] PulseInput33
[11] LocalBusRef
7-3* Process PI
Ctrl. 7-30 Process PI Normal/ Inverse Ctrl
*[0] Normal
[1] Inverse
7-31 Process PI Anti Windup
[0] Disable
*[1] Enable
7-32 Process PI Start Speed
0.0–200.0 Hz * 0.0 Hz
7-33 Process PI Proportional Gain
0.00–10.00 * 0.01
7-34 Process PI Integral Time
0.10–9,999 s * 9,999 s
7-38 Process PI Feed Forward Factor
0–400% * 0%
7-39 On Reference Bandwidth
0–200% * 5%
8-** Comm. and Options
8-0* General Settings
8-01 Control Site
*[0] Digital and ControlWord
[1] Digital only
[2] ControlWord only
8-02 Control Word Source
[0] None
*[1] FC RS-485
8-03 Control Word Timeout Time
0.1–6500 s * 1.0 s
8-04 Control Word Timeout Function
*[0] Off
[1] Freeze Output
[2] Stop
[3] Jogging
[4] Max. Speed
[5] Stop and trip
8-06 Reset Control Word Timeout
*[0] No Function
[1] Do reset
8-3* FC Port Settings
8-30 Protocol
*[0] FC
[2] Modbus
8-31 Address
1–247 * 1
8-32 FC Port Baud Rate
[0] 2400 Baud
[1] 4800 Baud

Table 1.9

*[2] 9600 Baud For choose FC Bus in 8-30
*[3] 19200 Baud For choose Modbus in 8-30
[4] 38400 Baud
8-33 FC Port Parity
*[0] Even Parity, 1 Stop Bit
[1] Odd Parity, 1 Stop Bit
[2] No Parity, 1 Stop Bit
[3] No Parity, 2 Stop Bits
8-35 Minimum Response Delay
0.001–0.5 * 0.010 s
8-36 Max Response Delay
0.100–10.00 s * 5.000 s
8-4* FC MC protocol set
8-43 FC Port PCD Read Configuration
*[0] None Expressionlimit
[1] [1500] Operation Hours
[2] [1501] Running Hours
[3] [1502] kWh Counter
[4] [1600] Control Word
[5] [1601] Reference [Unit]
[6] [1602] Reference %
[7] [1603] Status Word
[8] [1605] Main Actual Value [%]
[9] [1609] Custom Readout
[10] [1610] Power [kW]
[11] [1611] Power [hp]
[12] [1612] Motor Voltage
[13] [1613] Frequency
[14] [1614] Motor Current
[15] [1615] Frequency [%]
[16] [1618] Motor Thermal
[17] [1630] DC Link Voltage
[18] [1634] Heatsink Temp.
[19] [1635] Inverter Thermal
[20] [1638] SL Controller State
[21] [1650] External Reference
[22] [1651] Pulse Reference
[23] [1652] Feedback [Unit]
[24] [1660] Digital Input 18,19,27,33
[25] [1661] Digtial Input 29
[26] [1662] Analog Input 53 (V)
[27] [1663] Analog Input 53 (mA)
[28] [1664] Analog Input 60
[29] [1665] Analog Output 42 [mA]
[30] [1668] Freq. Input 33 [Hz]
[31] [1671] Relay Output [bin]
[32] [1672] Counter A
[33] [1673] Counter B
[34] [1690] Alarm Word
[35] [1692] Warning Word
[36] [1694] Ext. Status Word
8-5* Digital/Bus
8-50 Coasting Select
[0] DigitalInput
[1] Bus
[2] LogicAnd
*[3] LogicOr
8-51 Quick Stop Select
See par. 8-50 * [3] LogicOr
8-52 DC Brake Select
See par. 8-50 *[3] LogicOr
8-53 Start Select
See par. 8-50 *[3] LogicOr
8-54 Reversing Select
See par. 8-50 *[3] LogicOr
8-55 Set-up Select
See par. 8-50 *[3] LogicOr
8-56 Preset Reference Select
See par. 8-50 * [3] LogicOr
8-8* Bus Communication Diagnostics
8-80 Bus Message Count
0–0 N/A * 0 N/A
8-81 Bus Error Count
0–0 N/A * 0 N/A
8-82 Slave Messages Rcvd
0–0 N/A * 0 N/A
8-83 Slave Error Count
0–0 N/A * 0 N/A
8-9* Bus Jog / Feedback
8-94 Bus feedback 1
0x8000–0x7FFF * 0
13-** Smart Logic
13-0* SLC Settings
13-00 SL Controller Mode
*[0] Off
[1] On
13-01 Start Event
[0] False
[1] True
[2] Running
[3] InRange
[4] OnReference
[7] OutOfCurrentRange
[8] BelowILow
[9] AboveIHigh
[16] ThermalWarning
[17] MainOutOfRange
[18] Reversing
[19] Warning
[20] Alarm_Trip
[21] Alarm_TripLock
[22-25] Comparator 0-3
[26-29] LogicRule0-3
[33] DigitalInput_18
[34] DigitalInput_19
[35] DigitalInput_27
[36] DigitalInput_29
[38] DigitalInput_33
*[39] StartCommand
[40] DriveStopped
13-02 Stop Event
See par. 13-01 * [40] DriveStopped
13-03 Reset SLC
*[0] Do not reset
[1] Reset SLC
13-1* Comparators
13-10 Comparator Operand
*[0] Disabled
[1] Reference
[2] Feedback
[3] MotorSpeed
[4] MotorCurrent
[6] MotorPower
[7] MotorVoltage
[8] DCLinkVoltage
[12] AnalogInput53
[13] AnalogInput60
[18] PulseInput33
[20] AlarmNumber
[30] CounterA
[31] CounterB
13-11 Comparator Operator
[0] Less Than
*[1] Approximately equals
[2] Greater Than
13-12 Comparator Value
-9,999–9,999 * 0.0
13-2* Timers
13-20 SL Controller Timer
0.0–3,600 s * 0.0 s
13-4* Logic Rules
13-40 Logic Rule Boolean 1
See par. 13-01 *[0] False
[30] - [32] SL Timeout 0-2
13-41 Logic Rule Operator 1
*[0] Disabled
[1] And
[2] Or
[3] And not
[4] Or not
[5] Not and
[6] Not or
[7] Not and not
[8] Not or not
13-42 Logic Rule Boolean 2
See par. 13-40 * [0] False
13-43 Logic Rule Operator 2
See par. 13-41 *[0] Disabled
13-44 Logic Rule Boolean 3
See par. 13-40 * [0] False
13-5* States
13-51 SL Controller Event
See par. 13-40 *[0] False
13-52 SL Controller Action
*[0] Disabled
[1] NoAction
[2] SelectSetup1
[3] SelectSetup2
[10-17] SelectPresetRef0-7
[18] SelectRamp1
[19] SelectRamp2
[22] Run
[23] RunReverse
[24] Stop
[25] Qstop
[26] DCstop
[27] Coast
[28] FreezeOutput
[29] StartTimer0
[30] StartTimer1
[31] StartTimer2
[32] Set Digital Output A Low
[33] Set Digital Output B Low
[38] Set Digital Output A High
[39] Set Digital Output B High
[60] ResetCounterA
[61] ResetCounterB
14-** Special Functions
14-0* Inverter Switching
14-01 Switching Frequency
[0] 2 kHz
*[1] 4 kHz
[2] 8 kHz
[4] 16 kHz not available for M5
14-03 Overmodulation
[0] Off
*[1] On
14-1* Line power monitoring
14-12 Function at line imbalance
*[0] Trip
[1] Warning
[2] Disabled
14-2* Trip Reset
14-20 Reset Mode
*[0] Manual reset
[1-9] AutoReset 1-9
[10] AutoReset 10
[11] AutoReset 15
[12] AutoReset 20
[13] Infinite auto reset
[14] Reset at power-up
14-21 Automatic Restart Time
0–600s * 10s
14-22 Operation Mode
*[0] Normal Operation
[2] Initialization
14-26 Action At Inverter Fault
*[0] Trip
[1] Warning
14-4* Energy Optimizing
14-41 AEO Minimum Magnetization
40–75% * 66%
15-** Drive Information
15-0* Operating Data
15-00 Operating Days
15-01 Running Hours
15-02 kWh Counter
15-03 Power-ups
15-04 Overtemps
15-05 Over Volts
15-06 Reset kWh Counter
*[0] Do not reset
[1] Reset counter
15-07 Reset Running Hours Counter
*[0] Do not reset
[1] Reset counter
15-3* Fault Log
15-30 Fault Log: Error Code
15-4* Drive Identification
15-40 FC Type
15-41 Power Section
15-42 Voltage
15-43 Software Version
15-46 Adj. Freq. Drive Order. No
15-48 ID No
15-51 Adj. Freq. Drive Serial No
16-** Data Readouts 16-0* General Status
16-00 Control Word
0–0XFFFF
16-01 Reference [Unit]
-4,999–4,999 * 0.000
16-02 Reference %
-200.0–200.0% * 0.0%
16-03 Status Word
0–0XFFFF
16-05 Main Actual Value [%]
-200.0–200.0% * 0.0%
16-09 Custom Readout
Dep. on par. 0-31, 0-32 and 4-14
16-1* Motor Status
16-10 Power [kW]
16-11 Power [hp]
16-12 Motor Voltage [V]
16-13 Frequency [Hz]
16-14 Motor Current [A]
16-15 Frequency [%]
16-18 Motor Thermal [%]
16-3* Drive Status
16-30 DC Link Voltage
16-34 Heatsink Temp.
16-35 Inverter Thermal
16-36 Inv.Nom. Current
16-37 Inv. Max. Current
16-38 SL Controller State
16-5* Ref./Feedb.
16-50 External Reference
16-51 Pulse Reference
16-52 Feedback [Unit]

Table 1.10

16-6 Inputs/Outputs*	**16-65 Analog Output 42 [mA]**	0x8000–0x7FFF	*18-** Extended Motor Data*
16-60 Digital Input 18,19,27,33	**16-68 Pulse Input [Hz]**	*16-9* Diagnosis Readouts*	*18-8* Motor Resistors*
0–1111	**16-71 Relay Output [bin]**	**16-90 Alarm Word**	**18-80 Stator Resistance (High resolution)**
16-61 Digital Input 29	**16-72 Counter A**	0–0XFFFFFFFF	0.000–99.990 ohm * 0.000 ohm
0–1	**16-73 Counter B**	**16-92 Warning Word**	**18-81 Stator Leakage Reactance (High resolution)**
16-62 Analog Input 53 (volt)	*16-8* Ser. Com Bus/FC Port*	0–0XFFFFFFFF	0.000–99.990 ohm * 0.000 ohm
16-63 Analog Input 53 (current)	**16-86 FC Port REF 1**	**16-94 Ext. Status Word**	
16-64 Analog Input 60		0–0XFFFFFFFF	

Table 1.11

1.6 Troubleshooting

No.	Description	Warning	Alarm	Trip Lock	Error	Cause of Problem
2	Live zero error	X	X			Signal on terminal 53 or 60 is less than 50% of value set in *6-10 Terminal 53 Low Voltage*, *6-12 Terminal 53 Low Current*and *6-22 Terminal 54 Low Current*.
4	Mains phase loss[1)]	X	X	X		Missing phase on the supply side, or a voltage imbalance that is too high. Check supply voltage.
7	DC overvoltage1)	X	X			Intermediate circuit voltage exceeds the limit.
8	DC undervoltage1)	X	X			Intermediate circuit voltage drops below the “voltage warning low” limit.
9	Inverter overloaded	X	X			More than 100% load for too long.
10	Motor ETR overtemperature	X	X			Motor is too hot due to more than 100% load for too long.
11	Motor thermistor overtem-perature	X	X			The thermistor or the thermistor connection is disconnected.
12	Torque limit	X				Torque exceeds the value set in either par. 4-16 or 4-17.
13	Overcurrent	X	X	X		Inverter peak current limit is exceeded.
14	Earth fault	X	X	X		Discharge from output phases to ground.
16	Short-circuit		X	X		Short-circuit in the motor or on the motor terminals.
17	Control word timeout	X	X			No communication to the adjustable frequency drive.
25	Brake resistor short-circuited		X	X		Brake resistor is short-circuited, thus the brake function is disconnected.
27	Brake chopper short-circuited		X	X		Brake transistor is short-circuited, thus the brake function is disconnected.
28	Brake check		X			Brake resistor is not connected/working
29	Power board overtemp	X	X	X		Heatsink cut-out temperature has been reached.
30	Motor phase U missing		X	X		Motor phase U is missing. Check the phase.
31	Motor phase V missing		X	X		Motor phase V is missing. Check the phase.
32	Motor phase W missing		X	X		Motor phase W is missing. Check the phase.
38	Internal fault		X	X		Contact local Danfoss supplier.
44	Earth fault		X	X		Discharge from output phases to ground.
47	Control Voltage Fault		X	X		24 V DC may be overloaded.
51	AMT check U_{nom} and I_{nom}		X			Wrong setting for motor voltage and/or motor current.
52	AMT low I_{nom}		X			Motor current is too low. Check settings.
2.32 [59]	Current limit	X				VLT overload.
63	Mechanical Brake Low		X			Actual motor current has not exceeded the “release brake” current in the “start delay” time window.
80	Drive Initialized to Default Value		X			All parameter settings are initialized to default settings.
84	The connection between drive and LCP is lost				X	No communication between LCP and adjustable frequency drive
85	Button disabled				X	See parameter group 0-4* *LCP*
86	Copy fail				X	An error occurred while copying from adjustable frequency drive to LCP or vice versa.
87	LCP data invalid				X	Occurs when copying from LCP if the LCP contains erroneous data - or if no data was uploaded to the LCP.
88	LCP data not compatible				X	Occurs when copying from LCP if data are moved between adjustable frequency drives with major differences in software versions.
89	Parameter read-only				X	Occurs when trying to write to a read-only parameter.
3.54 [90]	Parameter database busy				X	LCP and RS485 connection are trying to update parameters simultaneously.
91	Parameter value is not valid in this mode				X	Occurs when trying to write an illegal value to a parameter.

No.	Description	Warning	Alarm	Trip Lock	Error	Cause of Problem
92	Parameter value exceeds the min/max limits				X	Occurs when trying to set a value outside the range.
nw run	**N**ot **W**hile **RUN**ning				X	Parameter can only be changed when the motor is stopped.
Err.	An incorrect password was entered				X	Occurs when using an incorrect password for changing a password-protected parameter.
[1] These faults may be caused by line power distortions. Installing a Danfoss line filter may rectify this problem.						

Table 1.12 Warnings and Alarms Code List

1.7 Specifications

1.7.1 Line Power Supply 1 x 200–240V AC

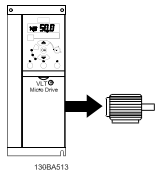
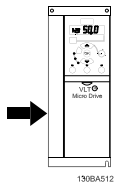
Normal overload 150% for 1 minute						
Adjustable frequency drive		**PK18**	**PK37**	**PK75**	**P1K5**	**P2K2**
Typical Shaft Output [kW]		**0.18**	**0.37**	**0.75**	**1.5**	**2.2**
Typical Shaft Output [HP]		**0.25**	**0.5**	**1**	**2**	**3**
IP 20		Frame M1	Frame M1	Frame M1	Frame M2	Frame M3
Output current						
	Continuous (3 x 200–240V) [A]	1.2	2.2	4.2	6.8	9.6
	Intermittent (3 x 200–240V) [A]	1.8	3.3	6.3	10.2	14.4
	Max. cable size:					
	(line power, motor) [mm² /AWG]	4/10				
Max. input current						
	Continuous (1 x 200–240V) [A]	3.3	6.1	11.6	18.7	26.4
	Intermittent (1 x 200–240V) [A]	4.5	8.3	15.6	26.4	37.0
	Max. electrical fuses [A]	See section Fuses.				
	Environment					
	Estimated power loss [W], Best case/ Typical[1)]	12.5/ 15.5	20.0/ 25.0	36.5/ 44.0	61.0/ 67.0	81.0/ 85.1
	Weight enclosure IP20 (lbs [kg])	2.43 [1.1]	2.43 [1.1]	2.43 [1.1]	3.53 [1.6]	6.61 [3.0]
	Efficiency [%], Best case/Typical[1)]	95.6/ 94.5	96.5/ 95.6	96.6/ 96.0	97.0/ 96.7	96.9/ 97.1

Table 1.13 Line Power Supply 1 x 200–240V AC

1. At rated load conditions.

1.7.2 Line Power Supply 3 x 200–240V AC

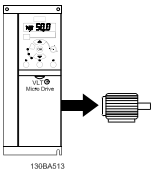
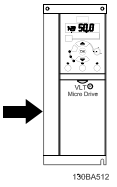
Normal overload 150% for 1 minute							
Adjustable frequency drive		**PK25**	**PK37**	**PK75**	**P1K5**	**P2K2**	**P3K7**
Typical Shaft Output [kW]		**0.25**	**0.37**	**0.75**	**1.5**	**2.2**	**3.7**
Typical Shaft Output [HP]		**0.33**	**0.5**	**1**	**2**	**3**	**5**
IP 20		Frame M1	Frame M1	Frame M1	Frame M2	Frame M3	Frame M3
Output current							
	Continuous (3 x 200–-240V) [A]	1.5	2.2	4.2	6.8	9.6	15.2
	Intermittent (3 x 200–240V) [A]	2.3	3.3	6.3	10.2	14.4	22.8
	Max. cable size:						
	(line power, motor) [mm² /AWG]	4/10					
Max. input current							
	Continuous (3 x 200–-240V) [A]	2.4	3.5	6.7	10.9	15.4	24.3
	Intermittent (3 x 200–240V) [A]	3.2	4.6	8.3	14.4	23.4	35.3
	Max. electrical fuses [A]	See section Fuses.					
	Environment						
	Estimated power loss [W], Best case/ Typical[1)]	14.0/ 20.0	19.0/ 24.0	31.5/ 39.5	51.0/ 57.0	72.0/ 77.1	115.0/ 122.8
	Weight enclosure IP20 (lbs [kg])	2.43 [1.1]	2.43 [1.1]	2.43 [1.1]	3.53 [1.6]	6.61 [3.0]	6.61 [3.0]
	Efficiency [%], Best case/Typical[1)]	96.4/ 94.9	96.7/ 95.8	97.1/ 96.3	97.4/ 97.2	97.2/ 97.4	97.3/ 97.4

Table 1.14 Line Power Supply 3 x 200–240V AC

1. At rated load conditions.

1.7.3 Line Power Supply 3x380–480 V AC

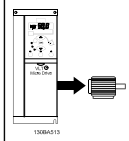
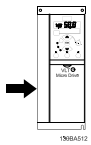
Normal overload 150% for 1 minute							
Adjustable frequency drive		**PK37**	**PK75**	**P1K5**	**P2K2**	**P3K0**	**P4K0**
Typical Shaft Output [kW]		**0.37**	**0.75**	**1.5**	**2.2**	**3.0**	**4.0**
Typical Shaft Output [HP]		**0.5**	**1**	**2**	**3**	**4**	**5**
IP 20		Frame M1	Frame M1	Frame M2	Frame M2	Frame M3	Frame M3
Output current							
	Continuous (3x380–440 V) [A]	1.2	2.2	3.7	5.3	7.2	9.0
	Intermittent (3x380–440 V) [A]	1.8	3.3	5.6	8.0	10.8	13.7
	Continuous (3x440–480 V) [A]	1.1	2.1	3.4	4.8	6.3	8.2
	Intermittent (3x440–480 V) [A]	1.7	3.2	5.1	7.2	9.5	12.3
	Max. cable size:						
	(line power, motor) [mm²/AWG]	4/10					
Max. input current							
	Continuous (3x380–440 V) [A]	1.9	3.5	5.9	8.5	11.5	14.4
	Intermittent (3x380–440 V) [A]	2.6	4.7	8.7	12.6	16.8	20.2
	Continuous (3x440–480 V) [A]	1.7	3.0	5.1	7.3	9.9	12.4
	Intermittent (3x440–480 V) [A]	2.3	4.0	7.5	10.8	14.4	17.5
	Max. electrical fuses [A]	See *1.3.4 Fuses*					
	Environment						
	Estimated power loss hp [W], Best case/ Typical[1)]	0.025 [18.5]/ 0.034 [25.5]	0.038 [28.5]/ 0.058 [43.5]	0.056 [41.5]/ 0.076 [56.5]	0.077 [57.5]/ 0.109 [81.5]	0.101 [75.0]/ 0.136 [101.6]	0.132 [98.5]/ 0.179 [133.5]
	Weight enclosure IP20 (lb [kg])	2.43 [1.1]	2.43 [1.1]	3.53 [1.6]	3.53 [1.6]	6.6 [3.0]	6.6 [3.0]
	Efficiency [%], Best case/ Typical[1)]	96.8/ 95.5	97.4/ 96.0	98.0/ 97.2	97.9/ 97.1	98.0/ 97.2	98.0/ 97.3

Table 1.15 Line Power Supply 3x380–480 V AC

1. *At rated load conditions.*

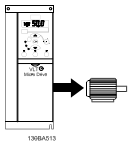
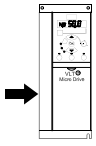
Normal overload 150% for 1 minute							
Adjustable frequency drive		**P5K5**	**P7K5**	**P11K**	**P15K**	**P18K**	**P22K**
Typical Shaft Output [kW]		**5.5**	**7.5**	**11**	**15**	**18.5**	**22**
Typical Shaft Output [HP]		**7.5**	**10**	**15**	**20**	**25**	**30**
IP 20		Frame M3	Frame M3	Frame M4	Frame M4	Frame M5	Frame M5
Output current							
	Continuous (3x380–440 V) [A]	12.0	15.5	23.0	31.0	37.0	43.0
	Intermittent (3x380–440 V) [A]	18.0	23.5	34.5	46.5	55.5	64.5
	Continuous (3x440–480 V) [A]	11.0	14.0	21.0	27.0	34.0	40.0
	Intermittent (3x440–480 V) [A]	16.5	21.3	31.5	40.5	51.0	60.0
	Max. cable size:						
	(line power, motor) [mm²/AWG]	4/10		16/6			
Max. input current							
	Continuous (3x380–440 V) [A]	19.2	24.8	33.0	42.0	34.7	41.2
	Intermittent (3x380–440 V) [A]	27.4	36.3	47.5	60.0	49.0	57.6
	Continuous (3x440–480 V) [A]	16.6	21.4	29.0	36.0	31.5	37.5
	Intermittent (3x440–480 V) [A]	23.6	30.1	41.0	52.0	44.0	53.0
	Max. electrical fuses [A]	See *1.3.4 Fuses*					
	Environment						
	Estimated power loss hp [W], Best case/ Typical[1)]	0.176 [131.0]/ 0.224 [166.8]	0.235 [175.0]/ 0.292 [217.5]	0.389 [290.0]/ 0.459 [342.0]	0.519 [387.0]/ 0.609 [454.0]	0.530 [395.0]/ 0.574 [428.0]	0.626 [467.0]/ 0.697 [520.0]
	Weight enclosure IP20 (lb [kg])	6.6 [3.0]	6.6 [3.0]				
	Efficiency [%], Best case/ Typical[1)]	98.0/ 97.5	98.0/ 97.5	97.8/ 97.4	97.7/ 97.4	98.1/ 98.0	98.1/ 97.9

Table 1.16 Line Power Supply 3x380–480 V AC

1. *At rated load conditions.*

1.8 General Technical Data

Protection and features

- Electronic thermal motor protection motor protection against overload.
- Temperature monitoring of the heatsink ensures that the adjustable frequency drive trips in case of overtemperature.
- The adjustable frequency drive is protected against short-circuits between motor terminals U, V, W.
- If a motor phase is missing, the adjustable frequency drive trips and issues an alarm.
- If a line phase is missing, the adjustable frequency drive trips or issues a warning (depending on the load).
- Monitoring of the intermediate circuit voltage ensures that the adjustable frequency drive trips if the intermediate circuit voltage is too low or too high.
- The adjustable frequency drive is protected against ground faults on motor terminals U, V, W.

Line power supply (L1/L, L2, L3/N)	
Supply voltage	200–240 V ±10%
Supply voltage	380–480 V ±10%
Supply frequency	50/60 Hz
Max. temporary imbalance between line phases	3.0% of rated supply voltage
True Power Factor	≥0.4 nominal at rated load
Displacement Power Factor (cosφ) near unity	(>0.98)
Switching on input supply L1/L, L2, L3/N (power-ups)	maximum 2 times/min.
Environment according to EN60664-1	overvoltage category III/pollution degree 2

The unit is suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical Amperes, 240/480 V maximum.

Motor output (U, V, W)	
Output voltage	0–100% of supply voltage
Output frequency	0–200 Hz (VVC^{plus}), 0–400 Hz (u/f)
Switching on output	Unlimited
Ramp times	0.05–3,600 s
Cable lengths and cross-sections:	
Max. motor cable length, shielded/armored (EMC-compliant installation)	50 ft [15 m]
Max. motor cable length, unshielded/unarmored	164 ft [50 m]
Max. cross-section to motor, line power*	
Connection to load sharing/brake (M1, M2, M3)	0.25 in [6.3 mm] insulated Faston plugs
Max. cross-section to load sharing/brake (M4, M5)	16mm^2/6AWG
Maximum cross-section to control terminals, rigid wire	1.5mm^2/16 AWG (2 x 0.75mm^2)
Maximum cross-section to control terminals, flexible cable	1mm^2/18 AWG
Maximum cross-section to control terminals, cable with enclosed core	0.5mm^2/20AWG
Minimum cross-section to control terminals	0.25mm^2

** See tables for line power supply for more information!*

Digital Inputs (Pulse/Enocder Inputs):	
Programmable digital inputs (pulse/encoder)	5 (1)
Terminal number	18, 19, 27, 29, 33,
Logic	PNP or NPN
Voltage level	0–24V DC
Voltage level, logic'0' PNP	< 5V DC
Voltage level, logic'1' PNP	> 10V DC
Voltage level, logic '0' NPN	> 19V DC
Voltage level, logic '1' NPN	< 14V DC
Maximum voltage on input	28V DC

Input resistance, R_i	approx. 4k
Max. pulse frequency at terminal 33	5000Hz
Min. pulse frequency at terminal 33	20Hz
Analog Inputs	
Number of analog inputs	2
Terminal number	53, 60
Voltage mode (Terminal 53)	Switch S200=OFF(U)
Current mode (Terminal 53 and 60)	Switch S200=ON(I)
Voltage level	0–10 V
Input resistance, R_i	approx. 10 kΩ
Max. voltage	20 V
Current level	0/4 to 20 mA (scaleable)
Input resistance, R_i	approx. 200 Ω
Max. current	30 mA

Analog output	
Number of programmable analog outputs	1
Terminal number	42
Current range at analog output	0/4-20 mA
Max. load to common at analog output	500 Ω
Max. voltage at analog output	17 V
Accuracy on analog output	Max. error: 0.8% of full scale
Scan interval	4 ms
Resolution on analog output	8 bit
Scan interval	4 ms

Control card, RS-485 serial communication	
Terminal number	68 (P,TX+, RX+), 69 (N,TX-, RX-)
Terminal number 61	Common for terminals 68 and 69
Control card, 24 V DC output	
Terminal number	12
Max. load (M1 and M2)	100 mA
Max. load (M3)	50 mA
Max. load (M4 and M5)	80 mA
Relay output:	
Programmable relay output	1
Relay 01 Terminal number	01-03 (break), 01-02 (make)
Max. terminal load (AC-1)1) on 01-02 (NO) (resistive load)	250V AC, 2 A
Max. terminal load (AC-15)[1)] on 01-02 (NO) (Inductive load @ cosφ 0.4)	250V AC, 0.2 A
Max. terminal load (DC-1)1) on 01-02 (NO) (resistive load)	30V DC, 2 A
Max. terminal load (DC-13)1) on 01-02 (NO) (inductive load)	24 V DC, 0.1A
Max. terminal load (AC-1)1) on 01-03 (NC) (resistive load)	250V AC, 2 A
Max. terminal load (AC-15)[1)] on 01-03 (NC) (Inductive load @ cosφ 0.4)	250V AC, 0.2A
Max. terminal load (DC-1)1) on 01-03 (NC) (resistive load)	30V DC, 2 A
Min. terminal load on 01-03 (NC), 01-02 (NO)	24V DC 10 mA, 24V AC 20 mA
Environment according to EN 60664-1	overvoltage category III/pollution degree 2

1) IEC 60947 part 4 and 5

Control card, 10 V DC output	
Terminal number	50
Output voltage	10.5 V ±0.5 V
Max. load	25 mA

NOTE!

All inputs, outputs, circuits, DC supplies and relay contacts are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Surroundings:	
Enclosure	IP 20
Enclosure kit available.	IP 21, TYPE 1
Vibration test	1.0 g
Max. relative humidity	5%-95% (IEC 60721-3-3; Class 3K3 (non-condensing) during operation
Aggressive environment (IEC 60721-3-3), coated	class 3C3
Test method according to IEC 60068-2-43 H2S (10 days)	
Ambient temperature	Max. 104°F [40°C]
Derating for high ambient temperature, see section on special conditions	
Minimum ambient temperature during full-scale operation	32°F [0°C]
Minimum ambient temperature at reduced performance	14°F [-10°C]
Temperature during storage/transport	-13°–+149°/158°F [-25°–+65°/70°C]
Maximum altitude above sea level without derating	3280 ft [1000 m]
Maximum altitude above sea level with derating	9842 ft [3000 m]
Derating for high altitude, see section on special conditions	
Safety standards	EN/IEC 61800-5-1, UL 508C
EMC standards, Emission	EN 61800-3, EN 61000-6-3/4, EN 55011, IEC 61800-3
EMC standards, Immunity	EN 61800-3, EN 61000-6-1/2, EN 61000-4-2, EN 61000-4-3, EN 61000-4-4, EN 61000-4-5, EN 61000-4-6
See section on special conditions	

1.9 Special Conditions

1.9.1 Derating for Ambient Temperature

The ambient temperature measured over 24 hours should be at least 9° F [5°C] lower than the max. ambient temperature.

If the adjustable frequency drive is operated at a high ambient temperature, the continuous output current should be decreased.

The adjustable frequency drive has been designed for operation at max 122° F [50°C] ambient temperature with one motor size smaller than nominal. Continuous operation at full load at 122° F [50°C] ambient temperature will reduce the lifetime of the adjustable frequency drive.

1.9.2 Derating for Low Air Pressure

The cooling capability of air is decreased at low air pressure.

For altitudes above 6,600 feet [2 km], contact Danfoss regarding PELV.

Below altitudes of 3,300 ft [1,000 m], no derating is necessary, but at 3,300 ft [1,000 m] and higher, the ambient temperature or maximum output current should be decreased.
Decrease the output by 1% per 328 ft [100 m] higher than an altitude of 3,300 ft [1,000 m], or reduce the max. ambient temperature by 1 degree per 656 ft [200 m].

1.9.3 Derating for Running at Low Speeds

When a motor is connected to an adjustable frequency drive, it is necessary to make sure that the cooling of the motor is adequate.
A problem may occur at low speeds in constant torque applications. Running continuously at low speeds – below half the nominal motor speed – may require additional air cooling. Alternatively, choose a larger motor (one size up).

1.10 Options for VLT® Micro Drive

Ordering No	Description
132B0100	VLT Control Panel LCP 11 w/o potentiometer
132B0101	VLT Control Panel LCP 12 with potentiometer
132B0102	Remote Mounting Kit for LCP incl. 10 ft [3 m] cable IP55 with LCP 11, IP21 with LCP 12
132B0103	Nema Type 1 kit for M1 frame
132B0104	Type 1 kit for M2 frame
132B0105	Type 1 kit for M3 frame
132B0106	De-coupling plate kit for M1 and M2 frames
132B0107	De-coupling plate kit for M3 frame
132B0108	IP21 for M1 frame
132B0109	IP21 for M2 frame
132B0110	IP21 for M3 frame
132B0111	DIN rail mounting kit for M1 and M2 frames
132B0120	Type 1 kit for M4 frame
132B0121	Type 1 kit for M5 frame
132B0122	De-coupling plate kit for M4 and M5 frames
132B0126	M1 frame spare parts kits
132B0127	M2 frame spare parts kits
132B0128	M3 frame spare parts kits
132B0129	M4 frame spare parts kits
132B0130	M5 frame spare parts kits
132B0131	Blank cover
130B2522	MCC 107 filter for 132F0001
130B2522	MCC 107 filter for 132F0002
130B2533	MCC 107 filter for 132F0003
130B2525	MCC 107 filter for 132F0005
130B2530	MCC 107 filter for 132F0007
130B2523	MCC 107 filter for 132F0008
130B2523	MCC 107 filter for 132F0009
130B2523	MCC 107 filter for 132F0010
130B2526	MCC 107 filter for 132F0012
130B2531	MCC 107 filter for 132F0014
130B2527	MCC 107 filter for 132F0016
130B2523	MCC 107 filter for 132F0017
130B2523	MCC 107 filter for 132F0018
130B2524	MCC 107 filter for 132F0020
130B2526	MCC 107 filter for 132F0022
130B2529	MCC 107 filter for 132F0024
130B2531	MCC 107 filter for 132F0026
130B2528	MCC 107 filter for 132F0028
130B2527	MCC 107 filter for 132F0030

Table 1.17

Danfoss line filters and brake resistors are available upon request.

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www.danfoss.com/drives

Danfoss Drives
4401 N. Bell School Rd.
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Fax: 1-815-639-8000
www.danfossdrives.com

Danfoss Drives
8800 W. Bradley Rd.
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Phone: 1-800-621-8806
1-414-355-8800
Fax: 1-414-355-6117
www.danfossdrives.com

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